

# HeelLink: A Smart Adaptive Insole for Idiopathic Toe Walking Rehabilitation

An early-stage smart corrective insole concept for conservative management of pediatric idiopathic toe walking

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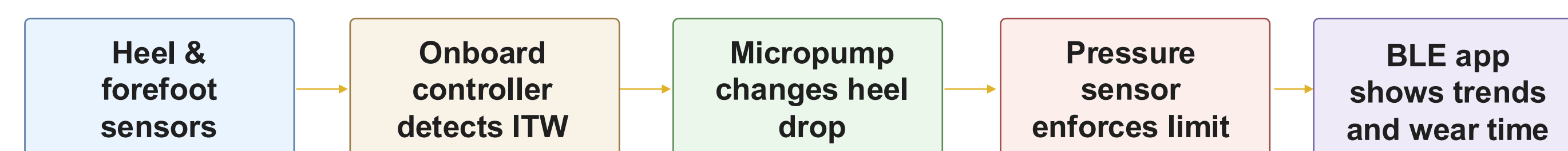
## INTRODUCTION

### Clinical problem

- Idiopathic toe walking (ITW) persists in a subset of children after age 5 and may require conservative intervention.
- Common options such as physical therapy, AFOs, and serial casting can improve motion or gait but often show variable real-world adherence.
- This project targeted a low-profile insole that can support gait retraining during normal daily activity.

## DEVICE CONCEPT

### Closed-loop corrective workflow



### Passive geometric correction

- Toe-walking is detected when forefoot force dominates and heel contact is absent or below threshold.
- A clinician-set pneumatic bladder raises heel drop within a 4–16 mm adjustment range.
- The design is intended to fit inside normal school shoes and log heel-strike %, wear time, and trend data.

### Key design distinctions

- Passive correction rather than punitive vibration alerts.
- Remote clinician adjustment with closed-loop gait data collection.
- Low-profile architecture intended for everyday pediatric footwear.

## DESIGN REQUIREMENTS (CTQS)

- Retain  $\geq 85\%$  of heel-cup depth under worst-case loading.
- Maintain safety factor  $\geq 2.0$  for the structural body material.
- Provide clinician-controlled heel-drop adjustment from 4–16 mm.
- Use long-term skin-contact materials with a credible biocompatibility pathway.
- Keep the device low profile enough to fit normal shoes.

## PROJECT SCOPE

### In Scope:

- A functional proof-of-concept prototype was fabricated.
- Engineering Feasibility
- Material Selection

### Out of Scope:

- No gait study, long-term wear study, or human-subject testing was performed in this phase.

## METHODS

### Development approach

- Literature review  $\rightarrow$  needs statements  $\rightarrow$  CTQ definition  $\rightarrow$  concept selection  $\rightarrow$  CAD development.
- Evaluation combined static FEA with a ISO 10993-1 biocompatibility review.

### Worst-case combined zone loading

Heel 450 N	Arch 150 N	Forefoot 550 N	Toes 180 N
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## MATERIAL COMPARISON

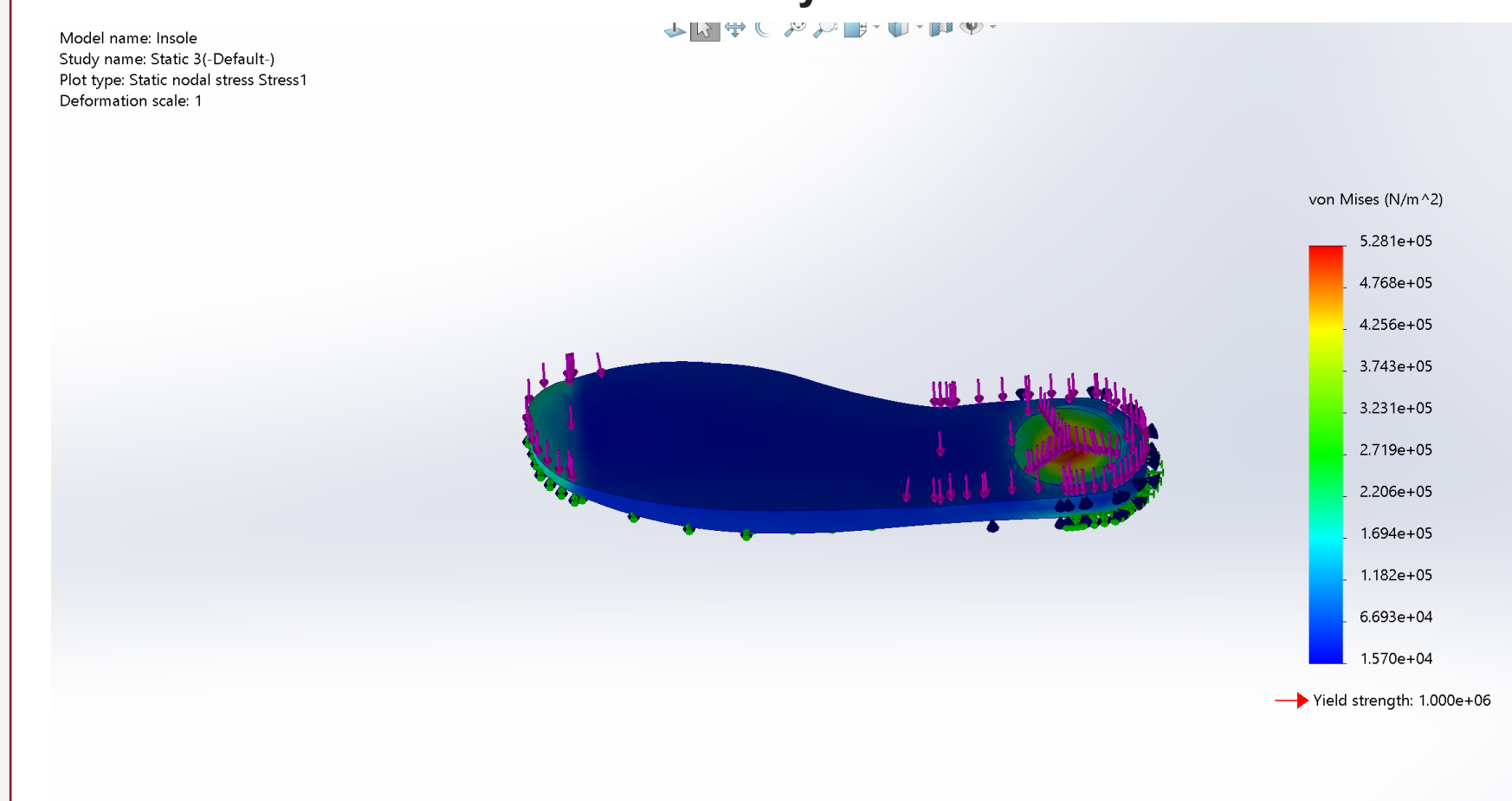
Property	EVA foam	SORTA-Clear 40
Elastic modulus	8.0 MPa	0.621 MPa
Poisson's ratio	0.35	0.47
Density	200 kg/m <sup>3</sup>	1080 kg/m <sup>3</sup>
Strength metric	Compressive strength 0.8 MPa	Tensile strength 5.52 MPa
Intended role	Structural insole body	Pneumatic bladder

## PROTOTYPE OUTCOME

- A proof-of-concept prototype demonstrated low-profile geometry and internal component packaging feasibility.
- Prototype development in this phase focused on build feasibility rather than performance validation.

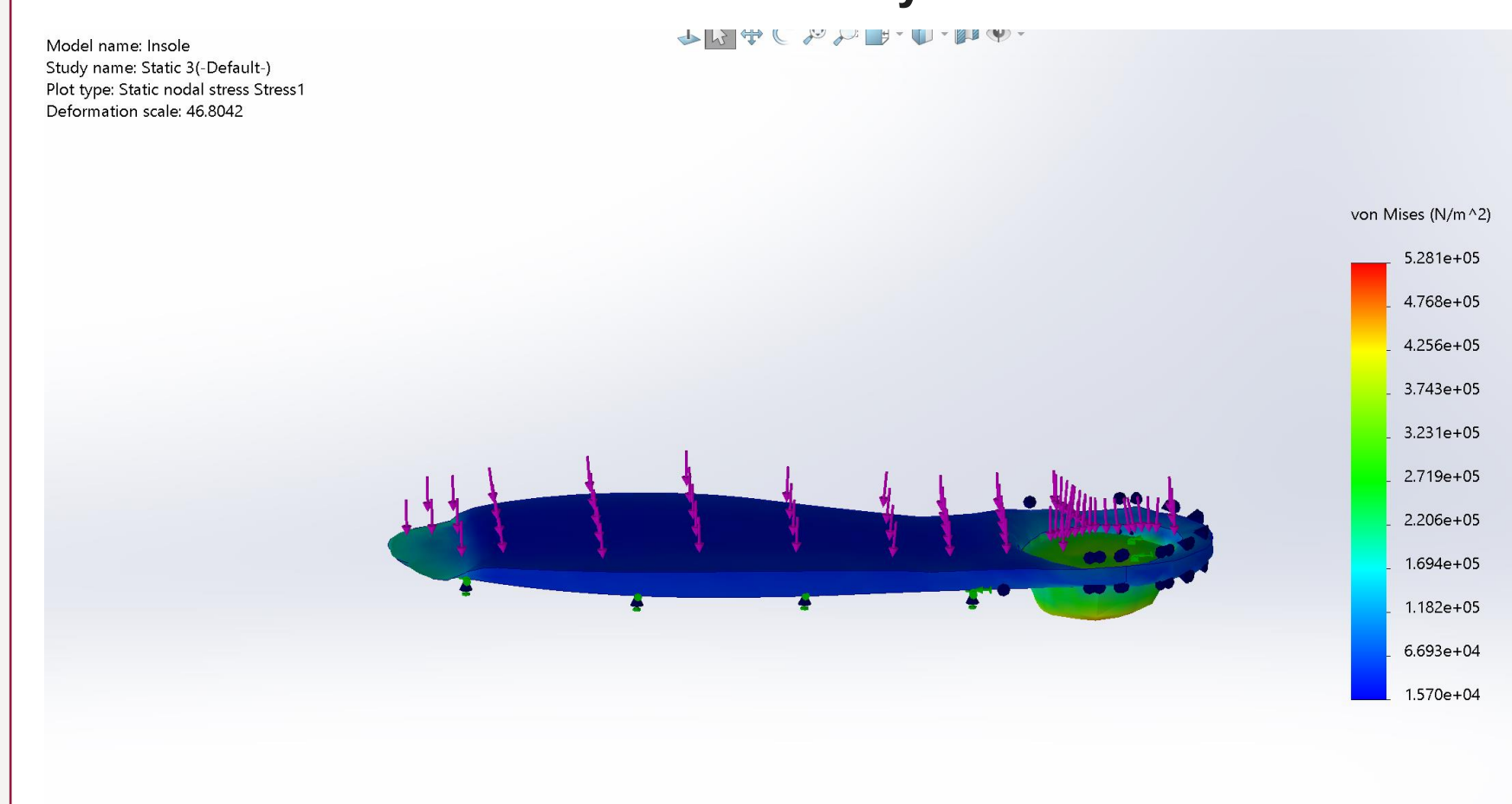
## FEA RESULTS

### EVA foam — selected structural body



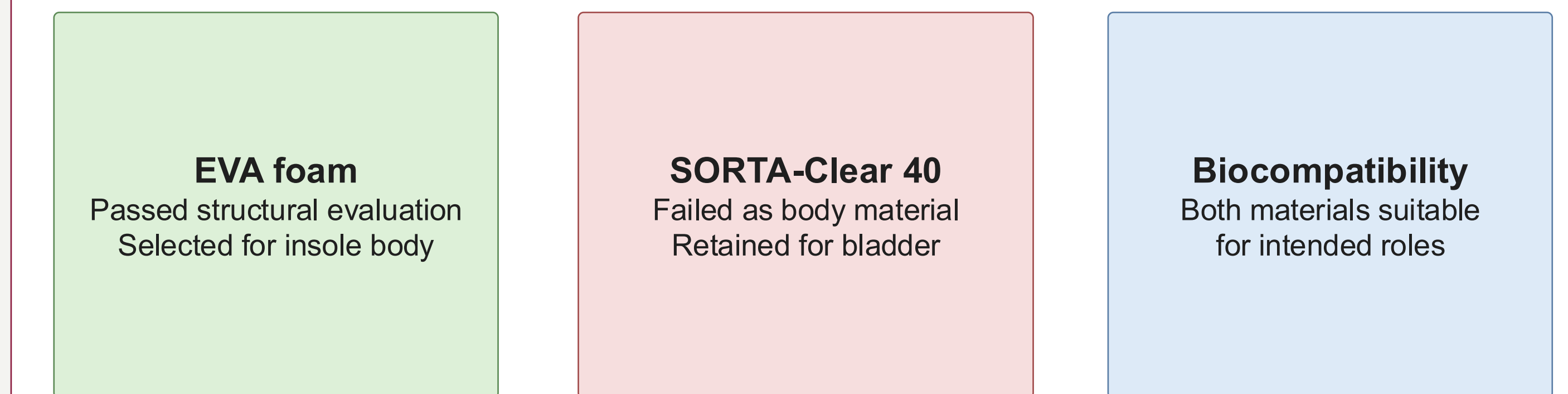
- Heel-cup geometry was preserved under the same worst-case loading scenario.
- Peak stress remained below the compressive limit; safety factor was  $> 2.0$ .
- Chosen as the structural insole body material.

### SORTA-Clear 40 — not suitable as body material



- Max URES = 4.886 mm at the heel versus a designed heel-cup depth of  $\sim 4$  mm.
- Failure mode was geometric collapse, not material fracture.
- Retained as the pneumatic bladder material because compliance is useful in that role.

## RESULTS AT A GLANCE



Desktop review supported cytotoxicity / sensitization / irritation rationale under ISO 10993-1; formal lot-level testing would still be required before clinical use.

## CONCLUSIONS AND NEXT STEPS

### Conclusions

- This project established an early-stage design basis for a smart corrective insole for ITW.
- FEA supported the material architecture of EVA foam for the body and SORTA-Clear 40 for the air bladder.

- The prototype showed build feasibility, but clinical performance remains untested.

### Future work

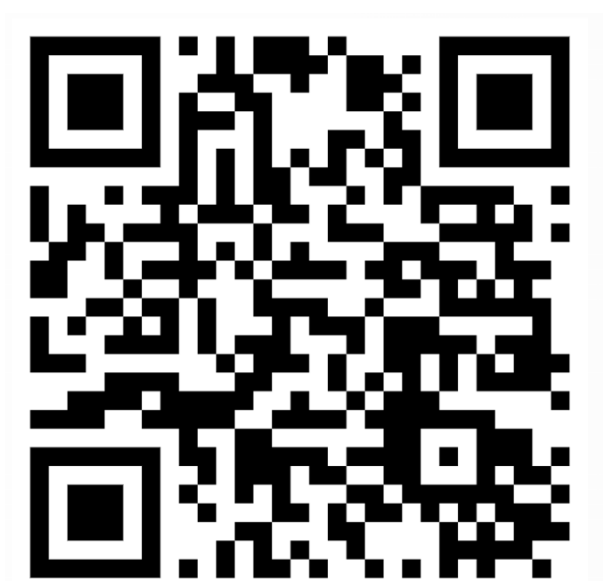
- Exact-material prototype fabrication and pneumatic bench testing.
- Fatigue testing, firmware/app development, and BLE integration.
- Clinical feasibility work with pediatric stakeholders.

## SELECT REFERENCES

- [1] Bauer et al. JAAOS, 2022
- [5] Caserta et al. Cochrane Review, 2019
- [7] Pollind et al. Biomed Sci Instrum, 2019
- [14] Verdejo & Mills, J Biomech, 2004
- [17] ISO 10993-1:2018

Full list in report

## SCAN FOR FULL REPORT



Methods, complete references, and supporting detail

## ACKNOWLEDGEMENTS

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